

Non-convergence Analysis of Probabilistic Direct Search

Cunxin Huang

Co-supervised by Dr. Zaikun Zhang and Prof. Xiaojun Chen

Graduate Student Forum of ORSC Mathematical Programming Branch
Chongqing, China, 2023

Department of Applied Mathematics
The Hong Kong Polytechnic University

Table of contents

1. Preliminaries

What is derivative-free optimization and why

Probabilistic direct search

2. Non-convergence analysis

Motivation and basic idea

Main results

3. Tightness of analysis

Almost zero gap

Tightness of assumptions

4. Conclusions

Preliminaries

What is derivative-free optimization and why

Derivative-free optimization (DFO)

- A branch of optimization
- **Do not use derivatives** (only use function evaluations)

What is derivative-free optimization and why

Derivative-free optimization (DFO)

- A branch of optimization
- Do not use derivatives (only use function evaluations)

Why DFO?

- Derivatives are not available
- Problems are often noisy (finite difference?)
- Function evaluations are expensive (e.g.: PDE simulation)

What is derivative-free optimization and why

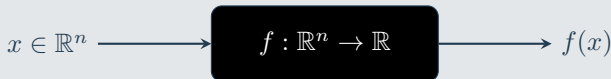
Derivative-free optimization (DFO)

- A branch of optimization
- **Do not use derivatives** (only use function evaluations)

Why DFO?

- Derivatives are **not available**
- Problems are often **noisy** (finite difference?)
- Function evaluations are **expensive** (e.g.: PDE simulation)

Typical situation: black box



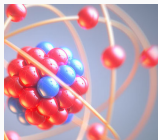
What is derivative-free optimization and why

Derivative-free optimization (DFO)

- A branch of optimization
- **Do not use derivatives** (only use function evaluations)

Why DFO?

- Derivatives are **not available**
- Problems are often **noisy** (finite difference?)
- Function evaluations are **expensive** (e.g.: PDE simulation)



Nuclear Physics



Machine Learning



Cosmology

In this talk, we consider the **unconstrained** problem

$$\min_{x \in \mathbb{R}^n} f(x),$$

where

- ∇f is **Lipschitz continuous**, although it cannot be evaluated,
- f is bounded below.

Algorithm 1: Probabilistic direct search based on [sufficient decrease](#)

Probabilistic direct search (PDS)

Algorithm 1: Probabilistic direct search based on [sufficient decrease](#)

Input: $x_0 \in \mathbb{R}^n$, $\alpha_0 \in (0, \infty)$, $0 < \theta < 1 < \gamma$.

Probabilistic direct search (PDS)

Algorithm 1: Probabilistic direct search based on [sufficient decrease](#)

Input: $x_0 \in \mathbb{R}^n$, $\alpha_0 \in (0, \infty)$, $0 < \theta < 1 < \gamma$.

for $k = 0, 1, \dots$ **do**

|

Probabilistic direct search (PDS)

Algorithm 1: Probabilistic direct search based on [sufficient decrease](#)

Input: $x_0 \in \mathbb{R}^n$, $\alpha_0 \in (0, \infty)$, $0 < \theta < 1 < \gamma$.

for $k = 0, 1, \dots$ **do**

 Select a finite set $D_k \subset \mathbb{R}^n$ randomly.

Probabilistic direct search (PDS)

Algorithm 1: Probabilistic direct search based on [sufficient decrease](#)

Input: $x_0 \in \mathbb{R}^n$, $\alpha_0 \in (0, \infty)$, $0 < \theta < 1 < \gamma$.

for $k = 0, 1, \dots$ **do**

 Select a finite set $D_k \subset \mathbb{R}^n$ randomly.

 (In this talk, assume D_k is a set of unit vectors for simplicity.)

Probabilistic direct search (PDS)

Algorithm 1: Probabilistic direct search based on [sufficient decrease](#)

Input: $x_0 \in \mathbb{R}^n$, $\alpha_0 \in (0, \infty)$, $0 < \theta < 1 < \gamma$.

for $k = 0, 1, \dots$ **do**

 Select a finite set $D_k \subset \mathbb{R}^n$ randomly.

 (In this talk, assume D_k is a set of unit vectors for simplicity.)

if $f(x_k + \alpha_k d) < f(x_k) - \alpha_k^2$ for some $d \in D_k$ **then**

 |

Probabilistic direct search (PDS)

Algorithm 1: Probabilistic direct search based on [sufficient decrease](#)

Input: $x_0 \in \mathbb{R}^n$, $\alpha_0 \in (0, \infty)$, $0 < \theta < 1 < \gamma$.

for $k = 0, 1, \dots$ **do**

 Select a finite set $D_k \subset \mathbb{R}^n$ randomly.

 (In this talk, assume D_k is a set of unit vectors for simplicity.)

if $f(x_k + \alpha_k d) < f(x_k) - \alpha_k^2$ for some $d \in D_k$ **then**

 Expand step size, and move to that point

Probabilistic direct search (PDS)

Algorithm 1: Probabilistic direct search based on [sufficient decrease](#)

Input: $x_0 \in \mathbb{R}^n$, $\alpha_0 \in (0, \infty)$, $0 < \theta < 1 < \gamma$.

for $k = 0, 1, \dots$ **do**

 Select a finite set $D_k \subset \mathbb{R}^n$ randomly.

 (In this talk, assume D_k is a set of unit vectors for simplicity.)

if $f(x_k + \alpha_k d) < f(x_k) - \alpha_k^2$ for some $d \in D_k$ **then**

 Expand step size, and move to that point

 Set $\alpha_{k+1} = \gamma \alpha_k$ and $x_{k+1} = x_k + \alpha_k d$.

else

Probabilistic direct search (PDS)

Algorithm 1: Probabilistic direct search based on [sufficient decrease](#)

Input: $x_0 \in \mathbb{R}^n$, $\alpha_0 \in (0, \infty)$, $0 < \theta < 1 < \gamma$.

for $k = 0, 1, \dots$ **do**

 Select a finite set $D_k \subset \mathbb{R}^n$ randomly.

 (In this talk, assume D_k is a set of unit vectors for simplicity.)

if $f(x_k + \alpha_k d) < f(x_k) - \alpha_k^2$ for some $d \in D_k$ **then**

 Expand step size, and move to that point

 Set $\alpha_{k+1} = \gamma \alpha_k$ and $x_{k+1} = x_k + \alpha_k d$.

else

 Shrink step size, and stand still

Probabilistic direct search (PDS)

Algorithm 1: Probabilistic direct search based on [sufficient decrease](#)

Input: $x_0 \in \mathbb{R}^n$, $\alpha_0 \in (0, \infty)$, $0 < \theta < 1 < \gamma$.

for $k = 0, 1, \dots$ **do**

 Select a finite set $D_k \subset \mathbb{R}^n$ randomly.

 (In this talk, assume D_k is a set of unit vectors for simplicity.)

if $f(x_k + \alpha_k d) < f(x_k) - \alpha_k^2$ for some $d \in D_k$ **then**

 Expand step size, and move to that point

 Set $\alpha_{k+1} = \gamma\alpha_k$ and $x_{k+1} = x_k + \alpha_k d$.

else

 Shrink step size, and stand still

 Set $\alpha_{k+1} = \theta\alpha_k$ and $x_{k+1} = x_k$.

Probabilistic direct search (PDS)

Algorithm 1: Probabilistic direct search based on [sufficient decrease](#)

Input: $x_0 \in \mathbb{R}^n$, $\alpha_0 \in (0, \infty)$, $0 < \theta < 1 < \gamma$.

for $k = 0, 1, \dots$ **do**

 Select a finite set $D_k \subset \mathbb{R}^n$ randomly. **How to select?**

 (In this talk, assume D_k is a set of unit vectors for simplicity.)

if $f(x_k + \alpha_k d) < f(x_k) - \alpha_k^2$ for some $d \in D_k$ **then**

 Expand step size, and move to that point

 Set $\alpha_{k+1} = \gamma\alpha_k$ and $x_{k+1} = x_k + \alpha_k d$.

else

 Shrink step size, and stand still

 Set $\alpha_{k+1} = \theta\alpha_k$ and $x_{k+1} = x_k$.

Probabilistic direct search (PDS)

Algorithm 1: Probabilistic direct search based on sufficient decrease

Input: $x_0 \in \mathbb{R}^n$, $\alpha_0 \in (0, \infty)$, $0 < \theta < 1 < \gamma$.

for $k = 0, 1, \dots$ **do**

 Select a finite set $D_k \subset \mathbb{R}^n$ randomly. **How to select?**

 (In this talk, assume D_k is a set of unit vectors for simplicity.)

if $f(x_k + \alpha_k d) < f(x_k) - \alpha_k^2$ for some $d \in D_k$ **then**

 Expand step size, and move to that point

 Set $\alpha_{k+1} = \gamma\alpha_k$ and $x_{k+1} = x_k + \alpha_k d$.

else

 Shrink step size, and stand still

 Set $\alpha_{k+1} = \theta\alpha_k$ and $x_{k+1} = x_k$.

Typical choice: $D_k = \{d_1, \dots, d_m\}$, where $d_i \stackrel{\text{i.i.d.}}{\sim} \text{Unif}(\mathcal{S}^{n-1})$

Illustration of how PDS works

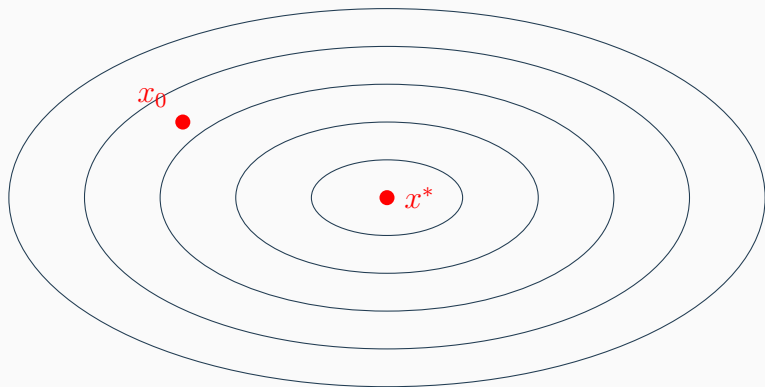


Illustration of how PDS works

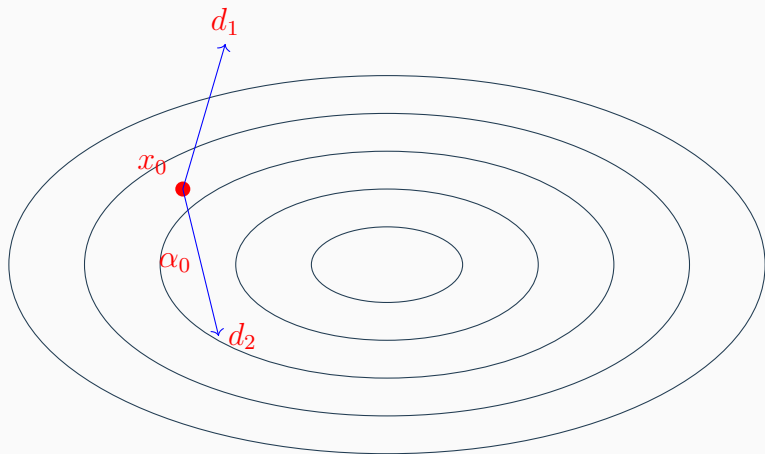


Illustration of how PDS works

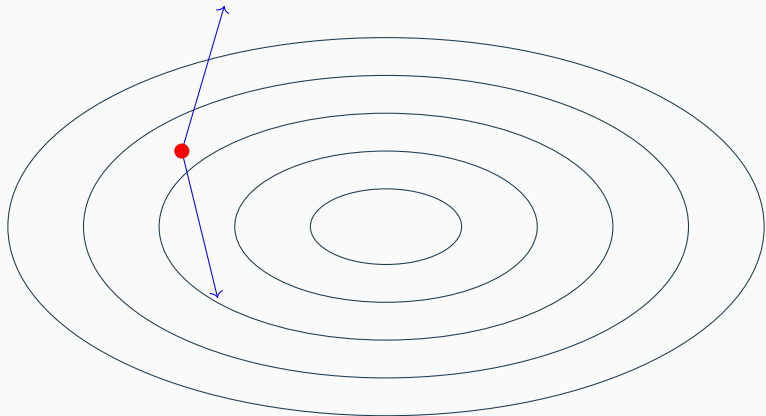


Illustration of how PDS works

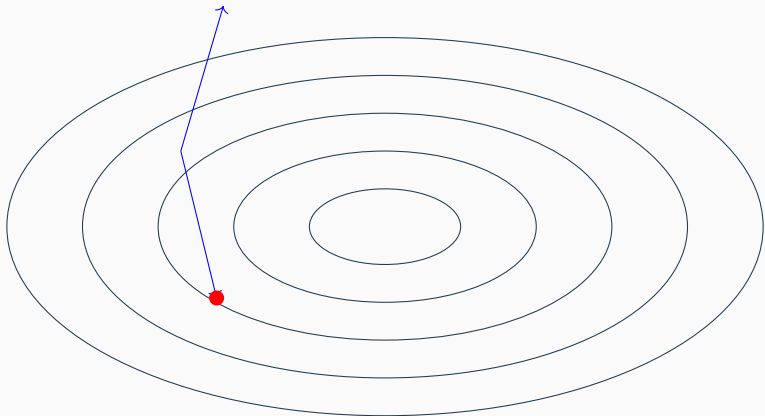


Illustration of how PDS works

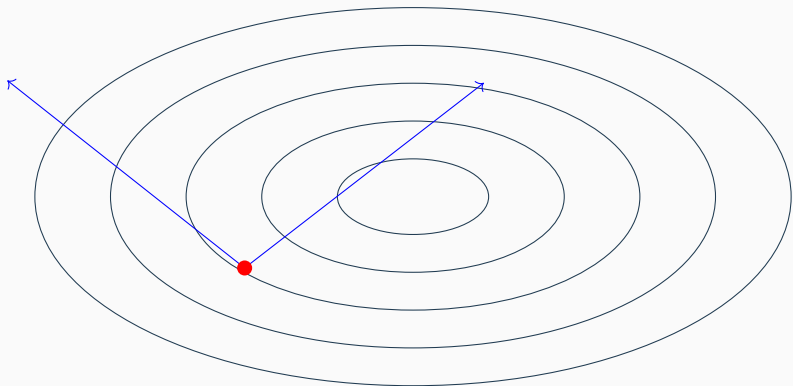


Illustration of how PDS works

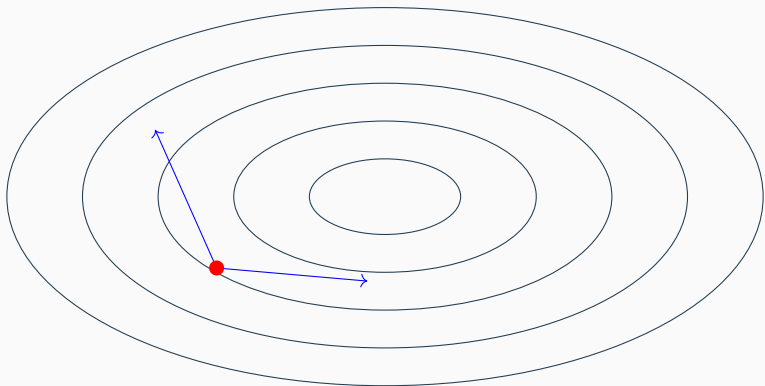


Illustration of how PDS works

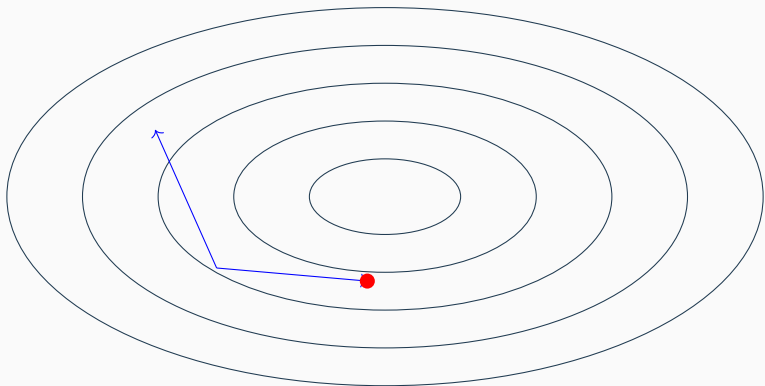


Illustration of how PDS works

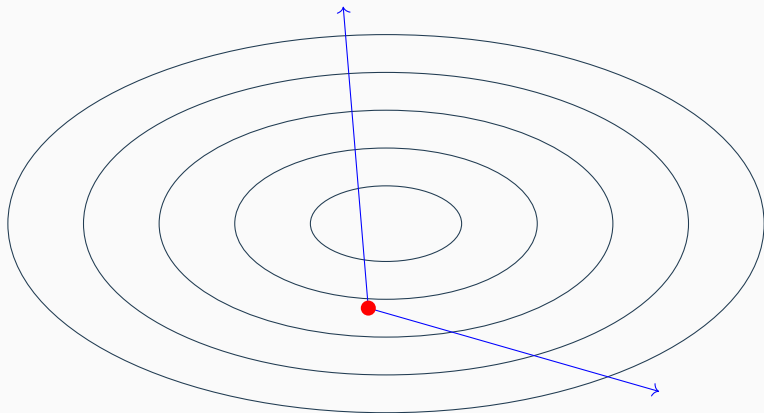


Illustration of how PDS works

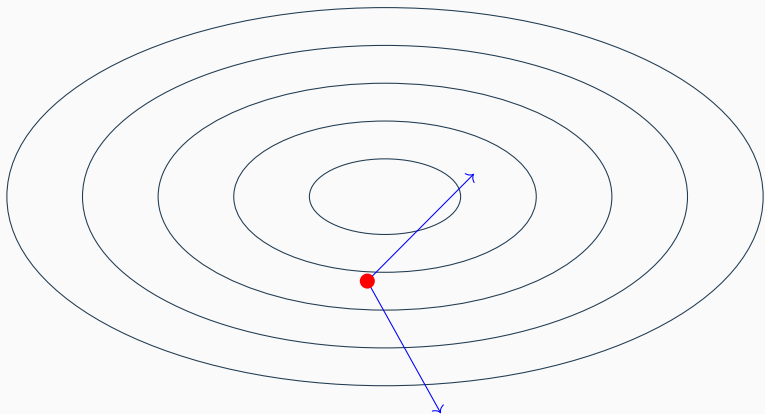


Illustration of how PDS works

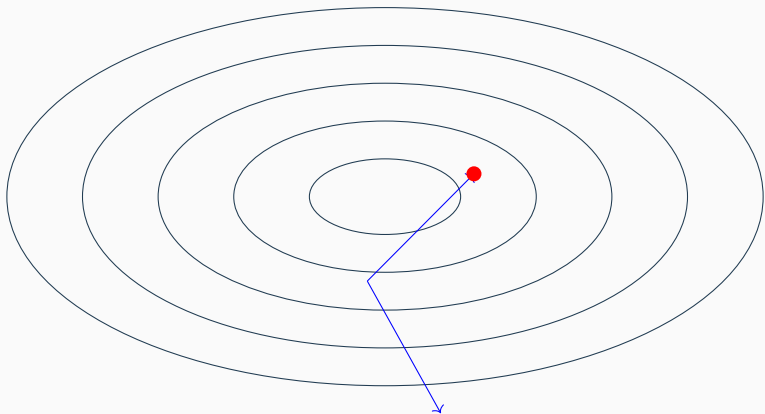


Illustration of how PDS works

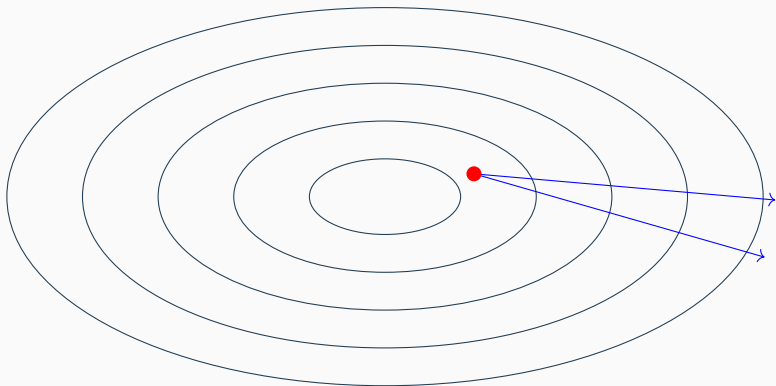


Illustration of how PDS works

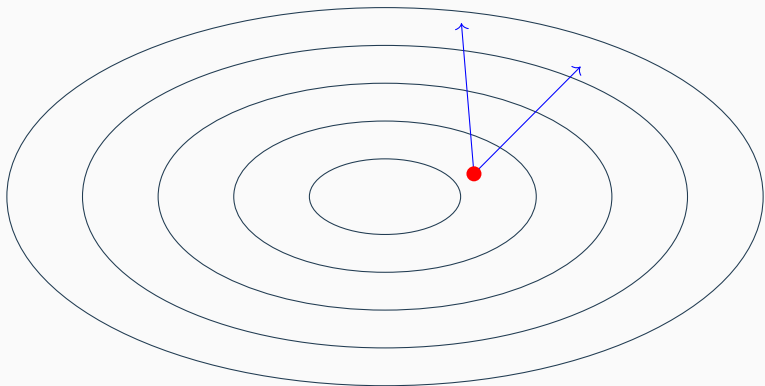
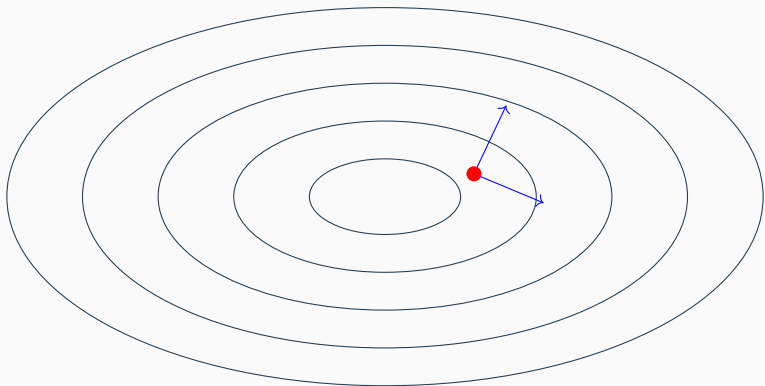


Illustration of how PDS works



Definition (Cosine measure)

Cosine measure for a finite set of nonzero vectors $D \subseteq \mathbb{R}^n$ w.r.t. a given vector $v \in \mathbb{R}^n$:

$$\text{cm}(D, v) = \max_{d \in D} \frac{d^\top v}{\|d\| \|v\|}.$$

Convergence theory

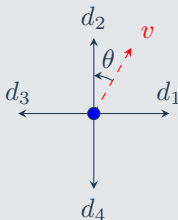
Definition (Cosine measure)

Cosine measure for a finite set of nonzero vectors $D \subseteq \mathbb{R}^n$ w.r.t. a given vector $v \in \mathbb{R}^n$:

$$\text{cm}(D, v) = \max_{d \in D} \frac{d^\top v}{\|d\| \|v\|}.$$

Example

$$\text{cm}(D, v) = \cos \theta$$



Convergence theory

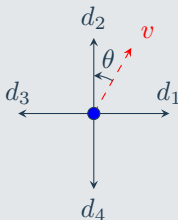
Definition (Cosine measure)

Cosine measure for a finite set of nonzero vectors $D \subseteq \mathbb{R}^n$ w.r.t. a given vector $v \in \mathbb{R}^n$:

$$\text{cm}(D, v) = \max_{d \in D} \frac{d^\top v}{\|d\| \|v\|}.$$

Example

$$\text{cm}(D, v) = \cos \theta$$



Measure the ability that “ D approximates v ”

Convergence theory

Definition (p -probabilistically κ -descent)

$(D_k)_{k \geq 0}$ is said to be p -probabilistically κ -descent, if

$$\mathbb{P}(\text{cm}(D_k, -g_k) \geq \kappa \mid D_0, \dots, D_{k-1}) \geq p \quad \text{for each } k \geq 0,$$

where $g_k = \nabla f(x_k)$.

Convergence theory

Definition (p -probabilistically κ -descent)

$(D_k)_{k \geq 0}$ is said to be p -probabilistically κ -descent, if

$$\mathbb{P}(\text{cm}(D_k, -g_k) \geq \kappa \mid D_0, \dots, D_{k-1}) \geq p \quad \text{for each } k \geq 0,$$

where $g_k = \nabla f(x_k)$.

Intuition:

each D_k is “good enough with lower-bounded probability”,
no matter what happened before

Convergence theory

Definition (p -probabilistically κ -descent)

$(D_k)_{k \geq 0}$ is said to be p -probabilistically κ -descent, if

$$\mathbb{P}(\text{cm}(D_k, -g_k) \geq \kappa \mid D_0, \dots, D_{k-1}) \geq p \quad \text{for each } k \geq 0,$$

where $g_k = \nabla f(x_k)$.

Intuition:

each D_k is “good enough with lower-bounded probability”,
no matter what happened before

Theorem (Gratton et al. 2015)

If $(D_k)_{k \geq 0}$ is p -probabilistically κ -descent with $\kappa > 0$ and

$$p = \log \theta / \log(\gamma^{-1} \theta),$$

then PDS converges with probability 1.

Corollary (Gratton et al. 2015)

If $D_k = \{d_1, \dots, d_m\}$, where $d_i \stackrel{i.i.d.}{\sim} \text{Unif}(\mathcal{S}^{n-1})$, then PDS is convergent if

$$m > \log_2 \left(1 - \frac{\log \theta}{\log \gamma} \right).$$

Corollary (Gratton et al. 2015)

If $D_k = \{d_1, \dots, d_m\}$, where $d_i \stackrel{i.i.d.}{\sim} \text{Unif}(\mathcal{S}^{n-1})$, then PDS is convergent if

$$m > \log_2 \left(1 - \frac{\log \theta}{\log \gamma} \right).$$

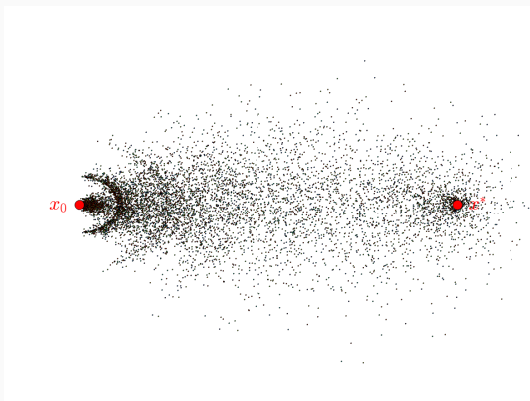
A natural question: what if

$$m \leq \log_2 \left(1 - \frac{\log \theta}{\log \gamma} \right)?$$

Practical choice and natural question

A natural question: what if

$$m \leq \log_2 \left(1 - \frac{\log \theta}{\log \gamma} \right)?$$



Non-convergence analysis

Motivation: non-convergence analysis matters

Many well-known algorithms have non-convergence analysis.

- S. Reddi, S. Kale, and S. Kumar. On the convergence of **Adam** and beyond. In Y. Bengio, Y. LeCun, T. Sainath, I. Murray, M. Ranzato, and O. Vinyals, editors, *International Conference on Learning Representations (ICLR 2018)*. Curran Associates, Inc., 2018.
- C. Chen, B. He, Y. Ye, and X. Yuan. The direct extension of **ADMM** for multi-block convex minimization problems is not necessarily convergent. *Math. Program.*, 155:57-79, 2016.
- W. Mascarenhas. The divergence of the **BFGS** and **Gauss Newton** methods. *Math. Program.*, 147:253-276, 2014.
- ...

Naive idea of non-convergence

Recall p -probabilistically κ -descent:

$$\mathbb{P}(\text{cm}(D_k, -g_k) \geq \kappa \mid D_0, \dots, D_{k-1}) \geq p \quad \text{for each } k \geq 0.$$

Naive idea of non-convergence

Recall p -probabilistically κ -descent:

$$\mathbb{P}(\text{cm}(D_k, -g_k) \geq \kappa \mid D_0, \dots, D_{k-1}) \geq p \quad \text{for each } k \geq 0.$$

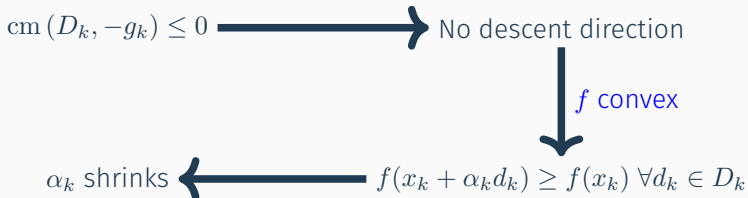
q -probabilistically ascent

$$\mathbb{P}(\text{cm}(D_k, -g_k) > 0 \mid D_0, \dots, D_{k-1}) \leq q \quad \text{for each } k \geq 0.$$

Naive idea of non-convergence

q -probabilistically ascent

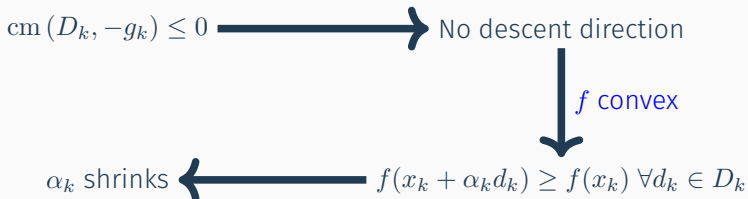
$$\mathbb{P}(\text{cm}(D_k, -g_k) > 0 \mid D_0, \dots, D_{k-1}) \leq q \quad \text{for each } k \geq 0.$$



Naive idea of non-convergence

q -probabilistically ascent

$$\mathbb{P}(\text{cm}(D_k, -g_k) > 0 \mid D_0, \dots, D_{k-1}) \leq q \quad \text{for each } k \geq 0.$$



non-convergence for convex functions



non-convergence in general

$(D_k)_{k \in \mathbb{N}}$ is
 q -probabilistically ascent

$(D_k)_{k \in \mathbb{N}}$ is
 q -probabilistically ascent



α_k shrinks with high probability

Establishment of non-convergence

$(D_k)_{k \in \mathbb{N}}$ is
 q -probabilistically ascent



α_k shrinks with high probability



$$\sum_{k=0}^{\infty} \alpha_k < \infty \quad \text{a.s. ?}$$

Establishment of non-convergence

$(D_k)_{k \in \mathbb{N}}$ is
 q -probabilistically ascent



α_k shrinks with high probability



$$\sum_{k=0}^{\infty} \alpha_k < \infty \quad \text{a.s. ?}$$



$$x_0 \notin \bar{B}(x^*, \sum_{k=0}^{\infty} \alpha_k)$$

Establishment of non-convergence

$(D_k)_{k \in \mathbb{N}}$ is
 q -probabilistically ascent



α_k shrinks with high probability



$$\sum_{k=0}^{\infty} \alpha_k < \infty \quad \text{a.s. ?}$$



$$x_0 \notin \bar{\mathcal{B}}(x^*, \sum_{k=0}^{\infty} \alpha_k)$$



$$\mathbb{P}(\text{Convergence}) < 1$$

- Define indicator function $Y_k = \mathbb{1}_{\{\text{cm}(D_k, -g_k) > 0\}}$
Indicator for “good” event

- Define indicator function $Y_k = \mathbb{1}_{\{\text{cm}(D_k, -g_k) > 0\}}$
Indicator for “good” event
- $\alpha_{k+1} \leq \gamma^{Y_k} \theta^{1-Y_k} \alpha_k$, when f is convex

- Define indicator function $Y_k = \mathbb{1}_{\{\text{cm}(D_k, -g_k) > 0\}}$
Indicator for “good” event
- $\alpha_{k+1} \leq \gamma^{Y_k} \theta^{1-Y_k} \alpha_k$, when f is convex
- $\alpha_k \leq \alpha_0 \prod_{i=0}^{k-1} \gamma^{Y_i} \theta^{1-Y_i} =: \alpha_0 U_k$

- Define indicator function $Y_k = \mathbb{1}_{\{\text{cm}(D_k, -g_k) > 0\}}$
Indicator for “good” event
- $\alpha_{k+1} \leq \gamma^{Y_k} \theta^{1-Y_k} \alpha_k$, when f is convex
- $\alpha_k \leq \alpha_0 \prod_{i=0}^{k-1} \gamma^{Y_i} \theta^{1-Y_i} =: \alpha_0 U_k$
- $\sum_{k=1}^{\infty} \alpha_k \leq \alpha_0 \sum_{k=1}^{\infty} U_k$

- Define indicator function $Y_k = \mathbb{1}_{\{\text{cm}(D_k, -g_k) > 0\}}$
Indicator for “good” event
- $\alpha_{k+1} \leq \gamma^{Y_k} \theta^{1-Y_k} \alpha_k$, when f is convex
- $\alpha_k \leq \alpha_0 \prod_{i=0}^{k-1} \gamma^{Y_i} \theta^{1-Y_i} =: \alpha_0 U_k$
- $\sum_{k=1}^{\infty} \alpha_k \leq \alpha_0 \sum_{k=1}^{\infty} U_k < \infty$ a.s. ?

Key to analysis

- Define indicator function $Y_k = \mathbb{1}_{\{\text{cm}(D_k, -g_k) > 0\}}$
Indicator for “good” event
- $\alpha_{k+1} \leq \gamma^{Y_k} \theta^{1-Y_k} \alpha_k$, when f is convex
- $\alpha_k \leq \alpha_0 \prod_{i=0}^{k-1} \gamma^{Y_i} \theta^{1-Y_i} =: \alpha_0 U_k$
- $\sum_{k=1}^{\infty} \alpha_k \leq \alpha_0 \sum_{k=1}^{\infty} U_k < \infty$ a.s. ?

Under q -probabilistically ascent assumption, can we find a constant ζ such that

$$\mathbb{P} \left(\sum_{k=1}^{\infty} U_k < \zeta \right) > 0?$$

Assumption

$\mathbb{P}(\text{cm}(D_k, -g_k) \leq 0 \mid D_0, \dots, D_{k-1}) \geq q > q_0$ for each $k \geq 0$,
where $q_0 = 1 - p_0 = \log \gamma / \log(\theta^{-1} \gamma)$.

Assumption

$\mathbb{P}(Y_k = 0 \mid Y_0, \dots, Y_{k-1}) \geq q > q_0$ for each $k \geq 0$,
where $q_0 = 1 - p_0 = \log \gamma / \log(\theta^{-1}\gamma)$.

Main results

Assumption

$$\mathbb{P}(Y_k = 0 \mid Y_0, \dots, Y_{k-1}) \geq q > q_0 \quad \text{for each } k \geq 0,$$

where $q_0 = 1 - p_0 = \log \gamma / \log(\theta^{-1}\gamma)$.

Result

1.

$$\mathbb{P}\left(\sum_{k=1}^{\infty} U_k < \infty\right) = 1$$

2.

$$\mathbb{P}\left(\sum_{k=1}^{\infty} U_k < \zeta\right) > 0 \iff \zeta > \frac{\theta}{1-\theta}$$

Main results

Assumption

$$\mathbb{P}(Y_k = 0 \mid Y_0, \dots, Y_{k-1}) \geq q > q_0 \quad \text{for each } k \geq 0,$$

where $q_0 = 1 - p_0 = \log \gamma / \log(\theta^{-1}\gamma)$.

Result

1.

$$\mathbb{P}\left(\sum_{k=1}^{\infty} U_k < \infty\right) = 1$$

2.

$$\mathbb{P}\left(\sum_{k=1}^{\infty} U_k < \zeta\right) > 0 \iff \zeta > \frac{\theta}{1-\theta}$$

Note that $\sum_{k=1}^{\infty} U_k = \sum_{k=1}^{\infty} \prod_{i=0}^{k-1} \gamma^{Y_i} \theta^{1-Y_i} \geq \theta / (1 - \theta)$

Main results

Assumption

$$\mathbb{P}(Y_k = 0 \mid Y_0, \dots, Y_{k-1}) \geq q > q_0 \quad \text{for each } k \geq 0,$$

where $q_0 = 1 - p_0 = \log \gamma / \log(\theta^{-1} \gamma)$.

Result

1.

$$\mathbb{P}\left(\sum_{k=1}^{\infty} U_k < \infty\right) = 1$$

2.

~~$$\mathbb{P}\left(\sum_{k=1}^{\infty} U_k < \zeta\right) > 0 \iff \zeta > \frac{\theta}{1 - \theta}$$~~

Main results

Assumption

$$\liminf_{k \rightarrow \infty} \mathbb{P}(Y_k = 0 \mid Y_0, \dots, Y_{k-1}) > q_0,$$

where $q_0 = 1 - p_0 = \log \gamma / \log(\theta^{-1} \gamma)$.

Result

1.

$$\mathbb{P}\left(\sum_{k=1}^{\infty} U_k < \infty\right) = 1$$

2.

$$\mathbb{P}\left(\sum_{k=1}^{\infty} U_k < \zeta\right) > 0 \iff \zeta > \frac{\theta}{1 - \theta}$$

Tightness of analysis

Let $D_k = \{d_1, \dots, d_m\}$, where $d_i \stackrel{\text{i.i.d.}}{\sim} \text{Unif}(\mathcal{S}^{n-1})$.

Recall that PDS is convergent if

$$m > \log_2 \left(1 - \frac{\log \theta}{\log \gamma} \right).$$

Almost zero gap

Let $D_k = \{d_1, \dots, d_m\}$, where $d_i \stackrel{\text{i.i.d.}}{\sim} \text{Unif}(\mathcal{S}^{n-1})$.

Recall that PDS is convergent if

$$m > \log_2 \left(1 - \frac{\log \theta}{\log \gamma} \right).$$

With our non-convergence analysis, PDS is non-convergent if

$$m < \log_2 \left(1 - \frac{\log \theta}{\log \gamma} \right).$$

Tightness of assumption

Natural question:

$$\mathbb{P}(\text{cm}(D_k, -g_k) \leq 0 \mid D_0, \dots, D_{k-1}) \geq q \not\geq q_0,$$

Tightness of assumption

Natural question:

$$\mathbb{P}(\text{cm}(D_k, -g_k) \leq 0 \mid D_0, \dots, D_{k-1}) \geq q \not\geq q_0,$$

Answer: NO

Tightness of assumption

Natural question:

$$\mathbb{P}(\text{cm}(D_k, -g_k) \leq 0 \mid D_0, \dots, D_{k-1}) \geq q \not\geq q_0,$$

Answer: NO

Example

We assume

- $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be gradient Lipschitz and strongly convex,
- $\theta = 1/2$ and $\gamma = 2$, $\Rightarrow q_0 = 1/2$
- $D_k = \{g_k/\|g_k\|\}$ or $D_k = \{-g_k/\|g_k\|\}$ with probability $1/2$, respectively,

then we have

$$\mathbb{P}\left(\lim_{k \rightarrow \infty} \|g_k\| = 0\right) = 1.$$

Conclusions

In this talk

- Non-convergence analysis for probabilistic direct search
- Tightness of non-convergence analysis

In this talk

- Non-convergence analysis for probabilistic direct search
- Tightness of non-convergence analysis

Future work

- Estimate the non-convergence probability
- Conduct non-convergence analysis for other frameworks

Thank you!

References I

- ▶ Biviano, A. et al. (2013). “CLASH-VLT: the mass, velocity-anisotropy, and pseudo-phase-space density profiles of the $z = 0.44$ galaxy cluster MACS J1206.2-0847”. *A&A* 558, A1:1–A1:22.
- ▶ Conn, A. R., Scheinberg, K., and Vicente, L. N. (2009). *Introduction to Derivative-Free Optimization*. Vol. 8. MOS-SIAM Ser. Optim. Philadelphia: SIAM.
- ▶ Durrett, R. (2010). *Probability: Theory and Examples*. Fourth. Camb. Ser. Stat. Probab. Math. Cambridge: Cambridge University Press.
- ▶ Fermi, E. and Metropolis, N. (1952). *Numerical solution of a minimum problem*. Tech. rep. Alamos National Laboratory, Los Alamos, USA.

References II

- ▶ Ghanbari, H. and Scheinberg, K. (2017). “Black-box optimization in machine learning with trust region based derivative free algorithm”. *arXiv:1703.06925*.
- ▶ Gratton, S. et al. (2015). “Direct search based on probabilistic descent”. *SIAM J. Optim.* 25, pp. 1515–1541.